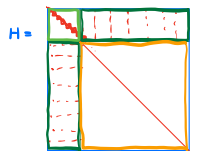


### Schon Trick



$H = \begin{bmatrix} B & E \\ E^T & C \end{bmatrix}$   
 $\Rightarrow \text{Max } g \iff \begin{bmatrix} B & E \\ E^T & C \end{bmatrix} \begin{bmatrix} \Delta x_c \\ \Delta x_p \end{bmatrix} = \begin{bmatrix} v \\ w \end{bmatrix}$

$\delta = h(x, y)$   
 $e = \delta - h(T, p)$   
 $\therefore \text{error}$   
 $\therefore \text{overall error}$   
 $\frac{1}{2} \sum_{i=1}^m \sum_{j=1}^n \|e_{ij}\|^2$   
 $= \frac{1}{2} \sum_{i=1}^m \sum_{j=1}^n \| \delta_{ij} - A(T; P)_{ij} \|^2$   
 we are adjusting the pose T & the camera P at the same time  
 Bundle Adjustment

$x = [T_1, \dots, T_m, P_1, \dots, P_n]^T$   
 $\frac{1}{2} \|f(x+\Delta x)\|^2$   
 $\approx \frac{1}{2} \sum_{i=1}^m \sum_{j=1}^n \|E_{ij} \Delta T_j + F_{ij} \Delta P_j\|^2$   
 we then stack all variables altogether:  
 $x_c = [T_1, \dots, T_m]^T \in \mathbb{R}^{6m}$   
 $x_p = [P_1, \dots, P_n]^T \in \mathbb{R}^{3n}$   
 $\frac{1}{2} \|f(x+\Delta x)\|^2 = \frac{1}{2} \|B \Delta x_c + E \Delta x_p\|^2$   
 $\text{Max } g$   
 $H = J^T J$  or  $J^T J + \lambda I$   
 $J = \begin{bmatrix} F & E \end{bmatrix}$   
 $J^T J = \begin{bmatrix} F^T F & F^T E \\ E^T F & E^T E \end{bmatrix}$